Integration of NFV with Distributed Orchestration into a WMN-based Disaster Network

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Abstract

This publication deals with integration of NFV with distributed orchestration into a WMN-based disaster network. The NFV orchestrator defined by ETSI is designed as a logically centralised unit and therefore includes the possibility of a single point of failure. Due to the environment of a disaster, a WMN node hosting this centralised orchestrator might get destroyed at events such as aftershocks or bursting fires resulting in a breakdown of the NFV infrastructure as it cannot be maintained and orchestrated anymore. To eliminate this aspect, requirements for a distributed NFV orchestration are defined. The requirements are categorized into architectural and orchestration specific aspects and are derived from the characteristics of a WMN and conditions of a disaster environment. For realising a distributed NFV orchestration in the WMN-based disaster network according to the defined requirements, a novel concept consisting of multiple logical layers is presented. Lastly, additional problem areas during the integration of NFV dealing with the realisation of virtualised network functions and virtual networks are presented and a possible solution is suggested.

1 Introduction

Due to natural disasters such as earthquakes, tsunamis, hurricanes and floods, as well as man-made disasters such as persistent power failures, it is essential to create structures to help the affected victims. In [1] an operations communication infrastructure is assumed to be crucial for the rescuing of victims and the management of the rescue teams. Unfortunately, existing communication infrastructures are often destroyed by the disaster, which makes the communication inside the affected regions impossible. [2] To establish a communication infrastructure for these disaster scenarios, a wireless mesh network (WMN) is suggested by [3]. The WMN consists of battery-supplied outdoor-routers connected to each other for creating a network. New nodes can be added to the WMN, while existing nodes might spontaneously leave the network because of an exhausted battery or aftershocks. By integrating and utilizing network function virtualization (NFV) in the WMN, the disaster network could be optimized regarding the availability, reliability, cost-efficiency, scalability, lower power consumption, adaptable network configuration and topology.

A crucial aspect regarding the integration of NFV into a WMN-based disaster network consists of the required centralized NFV orchestrator. A WMN-Node hosting the centralized orchestrator might get damaged, destroyed or lose its connectivity to large sections of the network due to additional disasters such as aftershocks and outbreaking fires. This is not beneficial, as it will result in losing the possibility to maintain and orchestrate the resources of the NFV infrastructure (NFVI) and the realized network services (NS). To prevent this scenario of a complete breakdown of the NFVI, the functionality of the orchestrator needs to be distributed among the WMN nodes of the disaster network.

Besides the elimination of the potential single point of failure of a centralized orchestrator through a possible redundancy realized by a distributed orchestrator, other improvements can be achieved. The workload of the centralized orchestrator can be distributed over several nodes of the distributed orchestrator. Additionally, the network traffic required for the management and orchestration functionality can be optimized through a distributed orchestrator. In case of a centralized orchestrator this kind of traffic must be forwarded form a maintained WMN-Node through the whole WMN to the orchestrator. This results in a high load on the connections in the WMN and an increased energy consumption which is needed for the transmission of the messages. In case of a decentralized orchestrator consisting of multiple instances, the traffic can be forwarded to the next local orchestrator instance. This would reduce the load on the links of the WMN. However, additional intra-orchestration traffic between the instances of the distributed orchestrator would be required and the decision-making process becomes more complex than the one of a centralized orchestrator.

This paper is structured as follows. Section 2 will shortly summarize and explain the NFV Management and Orchestration components as defined by ETSI. In Section 3 requirements for a distributed NFV orchestration in a WMN-based disaster network are defined and explained. Section 4 presents an architectural concept for a distributed NFV orchestration in a WMN-based disaster network, considering the defined requirements. In Section 5 additional problem areas during the integration of NFV dealing with the realisation of virtualised network functions and virtual networks are shortly explained and possible solutions are suggested. This paper will close with the outlining of the conclusions in Section 6.

2 Network Function Virtualisation Management and Orchestration

The NFV Management and Orchestration (NFV-MANO – see Figure 1) consists of three functional blocks: Virtual Infrastructure Manager (VIM), Virtual Network Function Manager (VNFM) and NFV Orchestrator (NFVO) as well as four data repositories: NS Catalogue, VNF Catalogue, NFVI Instances and NFVI Resources. [4]

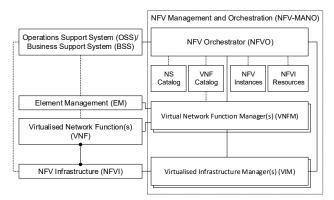


Figure 1 – NFV Framework specified by ETSI [5]

A VIM manages and controls the NFVI physical and virtual resources in a single domain. This implies that an NFV architecture may contain more than one VIM, each of them managing or controlling NFVI resources from a given infrastructure provider. Each VNFM is responsible for the management of the lifecycle of VNFs. A VNFM may be assigned with the management of a single or multiple VNF instance of the same or different type, including the possibility of a single VNFM for all active VNF instances in a certain domain. [4]

The catalogues and repositories are database used for storing different kind of information in the NFV-MANO. This information consists of predefined templates required for deployment of NS and VNFs (via the NS Catalogue and VNF Catalogue), as well as information regarding active NS and VNF instances (via the NFV Instances) and available and/or allocated NFVI resources (via the NFVI Resources). [4]

The logically centralized NFVO of the NFV-MANO aims to combine more than one function to create end-to-end services. Its functionality can be divided into two categories: the resource orchestration and the network service orchestration. The network service orchestration deals with the instantiation and lifecycle management of the network services. This includes the instantiation of the required VNF(s) in coordination with VNFM(s) and the topology management of the network service instances. Additionally, it is responsible for the policy management and evaluation for the network service and VNF instances (e.g. policies related to scaling, fault and performance, etc.). The resource orchestration provides the NFVI resource management across infrastructure domains including the reservation and allocation of NFVI resources to network services VNF instances in coordination with VIM(s). It is also responsible for the policy management and enforcement regarding aspects such as reservation and/or allocation policies. [5]

3 Requirements for a Distributed NFV Orchestration in a WMNbased Disaster Network

To the author's best conscience, the integration of NFV with distributed orchestration into a WMN-based disaster network has not yet been considered by other publications. Therefore, several requirements have been defined for the realization of this aspect. The requirements are separated into two different categories: *Architecture* specific and *Resource and Network Service Orchestration* specific aspects. The requirements have been derived from the characteristics of a WMN and the environment of a disaster. In the following sections, the requirements of each category are explained and justified in detail.

3.1 Architecture specific Requirements

Assuming an integration of the NFV framework specified by ETSI into the WMN-based disaster network, the centralized NFVO is inhibiting the possibility of a single point of failure as previously explained. The component responsible for the distributed NFV orchestration in a WMN-based disaster network therefore needs to fulfil architecture specific requirements:

3.1.1 Distributed and Decentralised

To prevent the possibility of a single point of failure, the architecture for the NFV orchestrator for the WMN-based disaster network needs to consist of a distributed and decentralised structure. This shall provide the possibility to realize redundant orchestrator units, which increases the availability of the orchestrator and therefore the availability of the complete NFVI and its realized network services.

3.1.2 Light-weight communication

Due to the distributed and decentralized architecture of the orchestrator, additional communication is required for the decision-making process of the orchestrator. The advantage of the previously mentioned reduction in the amount of traffic required for the node management over a central orchestrator and the resulting energy savings should not be lost. For this reason, the intracommunication between the instances of the distributed orchestrator should be as light-weight as possible. To enable a successful and useful output of the decision-making process, the intra-communication must ensure that the instances are constantly synchronized. Each instance should know and maintain the state and configuration of the other instances and their area of responsibility in the NFVI. This shall make it possible to seamlessly transfer the area of responsibility to another instance in the event of a failure of an incorrect instance.

3.1.3 Adaptability/Flexibility

As nodes can be added and removed to/from the WMN, the architecture of the distributed orchestrator must readjust and reconfigure itself if required to adapted to the changed in the network topology. This shall consist of the initialization of new instances for optimizing the management and orchestrator traffic in case of an increase of the network size and the deinitialization of existing instances if the network size decreases. In both cases, responsibilities for parts of the NFVI need to be transferred to other instances.

3.1.4 Robust/Fault-Tolerant

Due to the possibility of destroyed nodes in the WMNbased disaster network, the distributed architecture needs to be robust and fault-tolerant. Failing instances of the distributed orchestrator need to be replaced immediately. This might ether be realized by another instance taking over the responsibility of the failing instance of the initialization of a new instance.

3.1.5 Secure against violators

The distributed orchestrator must ensure that no attackers or violates can become part of the architecture. This shall prevent the decision-making process during the orchestrator from being influenced or compromised by incorrect information. Access to the distributed orchestrator for possible administrative activities (e.g. initialization of specific network services) should also be adequately protected.

3.2 Resource- and Network Service-Orchestration specific Requirements

NFV is designed to run on high volume servers, routers and switches in datacentres. The underlying hardware of the WMN-based disaster network is not able to provide this amount of hardware capacity as it consists of out-ofthe-shelf battery-supplied outdoor-routers, which should be highly energy-efficient to ensure a high lifespan of the disaster network. Due to these aspects, the resource and network service orchestration functionality of the distributed orchestrator needs to fulfil the following requirements:

3.2.1 Wireless connection awareness

The WMN-based disaster network is based on the wireless technology Wi-Fi. Since this type of technology is very susceptible to spontaneous and potentially lasting interferences, this aspect must be considered during the allocation of VNFs in the NFVI. In addition to the actual link quality, the general connection between the nodes of the WMN must be considered and constantly monitored. Adding WMN-Nodes could result in new and more performant paths discovered by the underlaying mesh routing protocol. In this case, a relocation of the VNFs might be required to optimize and improve the performance of the corresponding network service.

3.2.2 Continuous resource awareness

Due to the ability of self-configuration and selforganization, a WMN and thus the disaster network can be extended at any time. To extend the NFVI, the distributed orchestrator must seamlessly and automatically integrate the new resources. Also, the failure of WMN nodes and thus of NFVI-Point of Presences (NFVI-PoP) must also be regulated. There are two possible failures in the disaster network: a predictable failure due to an exhausted battery and an unforeseeable failure due to destroyed nodes because of events such as aftershocks and outbreaking fires. Both cases must be handled by the Resource-Orchestration functionality of the orchestrator.

3.2.3 Energy-Efficient resource allocation

Since the WMN nodes are battery-powered, the ability to optimize the energy consumption is one of the main reasons for integrating NFV into the WMN-based disaster network. The Resource- and Network Service-Orchestration functionality of the distributed orchestrator must allocate the network services as energy-efficiently as possible in the NFVI to ensure the longest possible lifespan and therefore the availability of the disaster network. For example, user-traffic flows in the WMN could be optimized so that services (such as web servers) are located close to the respective users. As a result, user traffic would not have to be forwarded unnecessarily in the WMN. If users move to another segment of the WMN, the corresponding service could also be migrated to the corresponding segment in the NFVI.

3.2.4 Autonomous deployment of network services

Due to the disaster environment, an administrator for the distributed orchestrator and therefore the NFVI cannot be expected. The orchestrator must therefore work as autonomously as possible. This also includes the initialization of network services currently required in the disaster network without any external trigger.

4 Architecture of a Distributed NFV Orchestrator for a WMNbased Disaster Network

To realize a distributed NFV-Orchestrator for a WMNbased disaster network, a concept of the orchestrator's architecture was developed, which makes it possible to realize the defined requirements. The architecture of the distributed orchestrator is based on five logical layers (see Figure 2) which are explained in the following sections: the WMN-based NFVI Layer, the VIM Layer, the NFVI-Clustered Layer, the Distributed Data Storage Layer and the NFV-Orchestration Layer.

4.1 WMN-based NFVI Layer

The WMN-based NFVI Layer consists of the actual battery-supplied outdoor-routers. Each WMN-Node in the

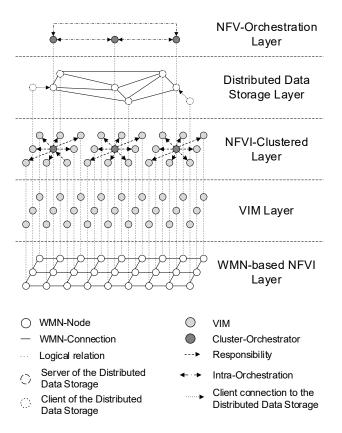


Figure 2 – Layers of an architecture for a distributed NFV orchestration in a WMN-based disaster network

disaster network is realizing a NFVI-PoP and provides its hardware and virtualization layer to the NFVI. Each node provides WMN-related as well as hardware- and virtualization layer-related information to the higher layers. The WMN-related information contains of the nodes knowledge about the WMN such as connections and routes as well as their capacity and quality, which are discovered by the used mesh routing protocol.

Previous research in [6] has evaluated the performance of different routing protocols regarding their use in the disaster network. The evaluation indicates that the protocol HWMP provides the best performance in terms of network adaptability.

4.2 VIM Layer

The VIM Layer defines a VIM for every NFVI-PoP in the WMN-based disaster network. A VIM is theoretically able to monitor multiple NFVI-PoPs. However, a VIM requires to permanently monitor the resources and the virtualization layer of its NFVI-PoPs for being able to notify an orchestrator at crossing of a defined threshold. By defining a VIM for every NFVI-PoP and therefore every WMN-Node, the required monitoring traffic remain locally on the nodes and is not forwarded through the WMN. Traffic regarding the management and orchestration of the NFVI-PoPs will only occur during the orchestration of the resources initialized by an orchestrator.

By retrieving and monitoring the information provided by the WMN-based NFVI Layer below, the VIM can provide meaningful information for an orchestrator.

4.3 NFVI-Clustered Layer

The NFVI-Clustered Layer consists of logical clusters on top of the VIM Layer. Each cluster defines the area of responsibility for a Cluster-Orchestrator responsible for orchestrating and managing the resources and network services in its cluster. The Cluster-Orchestrator realizes these aspects by communicating with the VIMs in his area of responsibility. Based on the retrievable information, a Cluster-Orchestrator can make decisions regarding the orchestration of resources within its cluster.

In the case of a new node being added to the WMN-based disaster network, the node will be connected to its locally nearest cluster. A new cluster will be created, in case of a cluster size increasing to a certain level, that a new node requires a significant number of hops in the WMN-based NFVI-Layer to reach its Cluster-Orchestrator. After initializing a new cluster including the assignment of a corresponding Cluster-Orchestrator, adjoining clusters might be rearranged to achieve evenly cluster sizes. Through the rearrangement of the clusters, adaptability and flexibility is achieved for the distributed orchestrator and thus for the WMN-based disaster network.

4.4 Distributed Data Storage Layer

The Distributed Data Storage Layer offers the possibility to store and save data and information in a reliable manner. An important feature of this layer is the ability to automatically create, distribute and manage redundancies of imported data and information. This makes it possible to achieve a high degree of reliability. The layer its realized by the Cluster-Orchestrators and an additional Backup-Node in each cluster, which are together creating and maintaining the reliable distributed data storage. The Backup-Node is added for an additional level of resilience to this layer. In case of a Cluster-Orchestrator failing, the data stored in the Distributed Data Storage Layer are still locally available in each cluster. The functionality of this layer is used for various aspects.

The Cluster-Orchestrators will use the layer to store and update the current NFV configurations and states in their cluster, which offers serval advantages. On the one hand, it relieves the actual communication between the Cluster-Orchestrators since any Cluster-Orchestrator can read in the complete configuration of other clusters at any time if it will be required. If a Cluster-Orchestrator fails, the configuration and state of the cluster is not lost, so that a new instance of a Cluster-Orchestrator can be put into operation immediately. Due to this aspect, it is important that the layer is automatically generating and maintaining redundancies of the stored data. Additionally, it needs to support a permanent synchronization of the stored files and the corresponding redundancies to ensure that the accessible data are always the most recent ones. The Distributed Data Storage Layer also provides the possibility to store the current topology of the WMN. A Cluster-Orchestrator can request the current connections and their capacity from the VIMs inside its cluster and store and maintain these information in the layer. By reading out all entries, a directed graph can be created that the Cluster-Orchestrator can use for the algorithm required during the allocation of VNFs.

Lastly, some services later realized as a VNF might create sensible data, which shall not be lost at a failure of the WMN-Node hosting this VNF. In this chase, the corresponding WMN-Node can create a client connection to the Distributed Data Storage Layer via its Cluster-Orchestrator and store the data of the VNF in the layer and not locally. Due to the automatically created redundancies, a new VNF can be created using the stored sensible data in case of a failure.

4.5 NFV-Orchestration Layer

The NFV-Orchestration Layer is used for the intraorchestration communication of the Cluster-Orchestrators. Due to the usage of the Distributed Data Storage Layer, a continuous transmission of configuration and state information of each cluster is not required. The communication taking place in this layer is event-driven and deals with the cluster-wide coordination regarding the NFV orchestration and the management and partitioning of the NFVI-Clustered Layer.

In case of the initialization of a new network service or the optimization of an already deployed network service, a Cluster-Orchestrator retrieves the available NFV configuration and state information of all clusters using the Distributed Data Storage Layer. Through this retrievable global view over the WMN-based NFVI Layer, the Cluster-Orchestrator will determinate the optimal placement and chaining of the required VNFs and notify the corresponding Cluster-Orchestrator with the appropriate configurations for their cluster. Additionally, NFV related failures will be handled via the intra-orchestration communication. In case of a local failure that cannot be solved by the corresponding Cluster-Orchestrator, such as the loss of a large proportion of resources in the local cluster, an event will be send to the other Cluster-Orchestrator indicating the requirement of an immediate intervention for bypassing and solving the failure by redeploying failing VNFs in adjoining clusters.

Regarding the management of the NFVI-Clustered Layer, the Cluster-Orchestrators will coordinate the partitioning of the clusters. This consists of the creation of a new clusters by initializing a new Cluster-Orchestrator, as well as the removal of existing clusters. In both cases a rearranging of the adjoining clusters is required. The case of a failed Cluster-Orchestrator is also dealt with by promoting a new Cluster-Orchestrator in the corresponding cluster or by taking over the responsibilities by an existing one.

The integration of a quorum-based voting procedure into this layer, in which other Cluster-Orchestrators must verify the proposal of a cluster-wide orchestration decision, is possible and conceivable, as this entails an additional synchronization within this layer.

5 Additional Problem Areas during the Integration of NFV into the WMN-based Disaster Network

In addition to the realisation of a distributed NFV orchestration for the WMN-based disaster network, other critical aspects must be considered during the integration of NFV. Those are the realisation of virtualised network functions and the realisation of separated virtual networks.

5.1 Realisation of Virtualised Network Functions

During the realisation of VNFs in the WMN-based disaster network, the limited available resources provided by the battery-supplied outdoor routers are a critical aspect. This aspect needs to be considered during the selection of the virtualisation technology used for the realisation of the VNFs. Mainly two kind of virtualisation technologies are utilized nowadays. Hypervisors-based virtualization and container-based virtualization are common technologies in use now. In hypervisor-based virtualisation, the hypervisor operates at hardware level, thus supporting standalone virtual machines that are isolated and independent of the host system. So, any operating system may be used on top. The disadvantages here are that a full operations system is installed to virtual machine and the emulation of virtual hardware devices incurs more overhead [7]. Two different types of hypervisors are classified - native hypervisors, which operate on top of the host's hardware and hosted hypervisors, which operate on top of the host's operating system. Container-based virtualisation can be considered as a lightweight alternative to hypervisor-based virtualization. Containers are running on top of shared operating system kernel of the underlying host machine. An advantage of container-based solutions is that the size of the disk images are smaller compared to hypervisor-based solutions. Container-based virtualization solutions also have some disadvantages, such as that no different operating system can run on top of the host (e.g. Windows on top of Linux) and containers do not isolate resources, because the kernel is exposed to the container, which may be an issue of security for multi-tenancy [7].

In a datacentre there are usually a sufficient amount of resources available for the extensive implementation of network functions using virtual machines. However, these resources cannot be provided in the WMN-based disaster network or it would be very energy-consuming compared to a container-based virtualisation. Additionally, according to [8] container-based solutions offer advantages such as low latency, low overhead, instant booting and energy efficiency especially in terms in networking, which would help increasing the overall performance and availability of the disaster network. [9] uses container-based VNFs for realising rate limiting, content filtering and firewalls on low cost edge devices, indicating that the realisation of container-based VNFs for the WMN-based disaster network is possible and promising. However, [10] lists various challenges such as the continuity, elasticity and portability for realising a container-based NFV platform, which need to be dealt with at the integration of a container-based VNFs into the WMN-based disaster network.

5.2 Realisation of Virtual Networks

The WMN-based disaster network will host various user groups such as the Federal Agency for Technical Relief (THW) of the German federal government, fire brigade and volunteers. Each of these user groups require its own separate network infrastructure with individual network services. Separate virtual networks are required to realize this aspect. Due to the permanent occurring changes in the network topology of the WMN through the possibility of new nodes being added and existing ones being removed due to aftershocks or an exhausted battery, the realization of the virtual networks requires to be highly dynamic and adaptable. An approach for the realisation of virtual networks, which is dynamic and adaptable to the environment of a WMN-based disaster network, consists of the use of tunnelling and encapsulation approaches such as VXLAN [11], NVGRE [12] and Geneve [13]. While these approaches are introducing additional overhead to the WMN, they enable a very high number of separate virtual networks and additionally offer the possibility of a seamless IP migration of a VNF by reconfiguring the corresponding tunnel endpoints.

6 Conclusion

In this publication a distributed NFV orchestration for a WMN-based disaster network was examined and presented in detail. Architecture specific and Resource- and Network Service-Orchestration specific requirements for the distributed orchestration have been defined. The requirements were derived from the characteristics of a WMN and the environment of a disaster. A concept for a distributed NFV orchestration in a WMN-based disaster network was presented, which consists of the logical clustering of the WMN. Each cluster is maintained and orchestrated by a Cluster-Orchestrator. Cluster-wide coordination regarding the NFV orchestration is achieved via the intra-orchestration communication. To realize this concept an architecture is proposed consisting of five logical layers with each layer fulfilling a certain functionality. Those layers are the WMN-based NFVI Layer, the VIM Layer, the NFVI-Clustered Layer, the Distributed Data Storage Layer and the NFV-Orchestration Layer. Through this proposed concept a distributed NFV orchestration for a WMN-based disaster network can be achieved which is among other things adaptable and robust. Lastly, problems related to the realisation of VNFs and virtual networks in the WMN-based disaster network have been highlighted, including an outlook on the solution.

7 Literature

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